



Machine Tool Control Technology Developed at UBC-MAL

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摘要(Abstract)

加拿大英屬哥倫比亞大學製造自動化實驗室 自 1986 年起開始發展金屬切削力學、工具機振動 理論、虛擬切削、工具機監控與控制系統。本文以 9軸CNC工具機為例,介紹本實驗室的研發現況。

The Manufacturing Automation Laboratory (MAL) at the University of British Columbia has been conducting research in metal cutting mechanics, machine tool vibrations, virtual machining, machine tool monitoring and CNC system design since 1986. This article presents the highlights of our research activities in multi-axis machine tool including Virtual CNC and a novel, 9-axis precision micromachining center.

Introduction

MAL has developed a virtual CNC design kit that allows automatic configuration of any 5 axis serial kinematic machine tool driven by linear or ball screw drives. The virtual CNC has been developed in MATLAB Simulink environment where the user can define the kinematic configuration of the machine; select drives with their friction, structural properties



including its vibration characteristics, and velocity acceleration – jerk limits; trajectory profiles which include the shape of velocity changes along the path; splining motion along the multi-axis curved paths; compensating future contouring errors by predicting them few hundred blocks ahead and compensating them; selecting various control methods for high precision tracking with friction compensation and active damping of vibrations; and compensation of position dependent and position independent volumetric errors of machine tools. Virtual CNC predicts the total machining time for the part, and all the states at the servo sampling intervals, such as position-velocity-acceleration-jerk-motor torque tracking error on each drive as well as the contouring errors left on the part due to CNC dynamics. When the Virtual CNC is connected to a digital signal

processing board with a real time operating system with MATLAB to C converter/compiler, it automatically becomes a real CNC to control physical machine tools.

UBC MAL's CNC is used to conduct basic research, teach CNC design to students and demonstrate the new methods to industrial clients for technology transfer and licensing. The features of the CNC are outlined as follows.

Modular Virtual/Real Time CNC

Virtual CNC has five major modules as shown in Figure 1: Axis configuration, Tool Path input, Trajectory Generation, Axis Control, Simulation and Real Time CNC.



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